

Proof of the Angle Change Invariant Model

Let u_{ax} and u_{ay} be the velocity of Ball A before the collision along the Collision and Sweep Axes, respectively. Let v_{ax} and v_{ay} be the velocity of Ball A after the collision along the Collision and Sweep Axes, respectively. Likewise, let u_{bx} , u_{by} , v_{bx} , and v_{by} be the four velocities for Ball B. Let u_{mx} , u_{my} , v_{mx} , and v_{my} be the average velocities of the two balls along the Collision and Sweep Axis before and after the collision. That is,

$$\begin{aligned}u_{mx} &= \frac{1}{2}(u_{ax} + u_{bx}), \\u_{my} &= \frac{1}{2}(u_{ay} + u_{by}), \\v_{mx} &= \frac{1}{2}(v_{ax} + v_{bx}), \\v_{my} &= \frac{1}{2}(v_{ay} + v_{by}).\end{aligned}\tag{A1}$$

Assuming perfectly elastic balls we know that $u_{my} = v_{my}$ because there is no change of velocity along the Sweep Axis. Thus, only the velocities along the Collision Axis, u_{mx} and v_{mx} are not constrained to be equal.

Given the pre-collision velocities, the post-collision velocities can be calculated as (e.g., Halliday et al, 1993)

$$v_{ax} = \frac{m_a - m_b}{m_a + m_b}u_{ax} + \frac{2m_b}{m_a + m_b}u_{bx}\tag{A2}$$

and

$$v_{bx} = \frac{2m_a}{m_a + m_b}u_{ax} + \frac{m_b - m_a}{m_a + m_b}u_{bx},\tag{A3}$$

where m_a and m_b are the masses of Balls A and B, respectively. Similar equations can be constructed for u_{ax} and u_{bx} .

From Equations in A2 and A3, we know that

$$\begin{aligned}
v_{mx} &= \frac{1}{2}(v_{ax} + v_{bx}) \\
&= \frac{1}{2} \left[\left(\frac{m_a - m_b}{m_a + m_b} u_{ax} + \frac{2m_b}{m_a + m_b} u_{bx} \right) + \left(\frac{2m_a}{m_a + m_b} u_{ax} + \frac{m_b - m_a}{m_a + m_b} u_{bx} \right) \right] \\
&= \frac{1}{2} \left[\frac{3m_a - m_b}{m_a + m_b} u_{ax} + \frac{3m_b - m_a}{m_a + m_b} u_{bx} \right],
\end{aligned} \tag{A4}$$

and similarly for u_{mx} . We are interested in the change in the average Collision Axis velocity.

That is,

$$\begin{aligned}
\delta = u_{mx} - v_{mx} &= \frac{1}{2} \left[u_{ax} \left(1 - \frac{3m_a - m_b}{m_a + m_b} \right) + u_{bx} \left(1 - \frac{3m_b - m_a}{m_a + m_b} \right) \right] \\
&= \frac{1}{2} \left[\frac{2m_b - 2m_a}{m_a + m_b} u_{ax} + \frac{2m_a - 2m_b}{m_a + m_b} u_{bx} \right] \\
&= \frac{m_b - m_a}{m_a + m_b} u_{ax} + \frac{m_a - m_b}{m_a + m_b} u_{bx} \\
&= \frac{m_b - m_a}{m_a + m_b} (u_{ax} - u_{bx})
\end{aligned} \tag{A5}$$

For a collision to occur $u_{ax} - u_{bx}$ must be positive. Thus, we have that,

$$\begin{aligned}
\delta &= 0 \text{ if } m_a = m_b, \\
\delta &> 0 \text{ if } m_a < m_b, \\
\delta &< 0 \text{ if } m_a > m_b.
\end{aligned} \tag{A6}$$

For a linear collision, if the average Collision Axis velocity increases, Ball A is heavier, if it decreases, Ball B is heavier, and if it remains unchanged, the balls have equal mass. For a collision with a non-zero Sweep Axis component that does not change after the collision, α from Figure 4 is positive if Ball B is heavier and negative if Ball A is heavier.